Image Acquisition Software – 2 version on 2 computer (ie Bigdog and Guidedog)
Go –
BOOT
  call grasp_boot
BGR
telnet and issue BGR command
GO
generate data.
  setup controller and go
  while waiting for done
    abort?
    update SM_IC
  get image
  done
MOVIE
generate data
  setup controller and go
  wait for data
    aborts
    update SM IC
  get image
  done.

Go_rec –
Forks grasp_reciever
Forks grasp_irsave when data is ready.

Grasp_ir_save
UPD data from sgir
Post on SHM_DP

SHM_DP

Dpserver
Services data pineline.